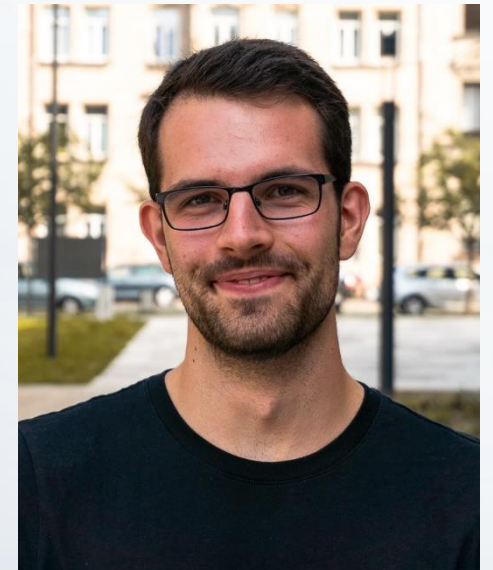


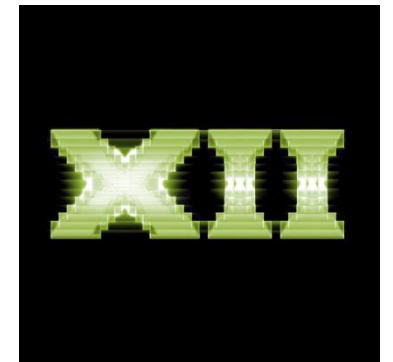
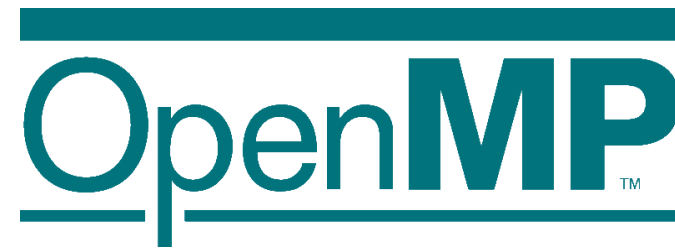
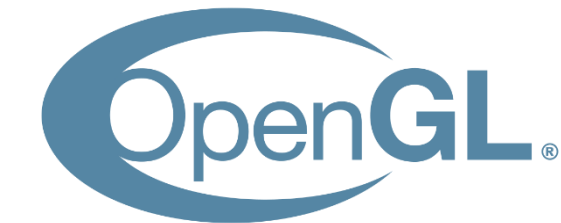
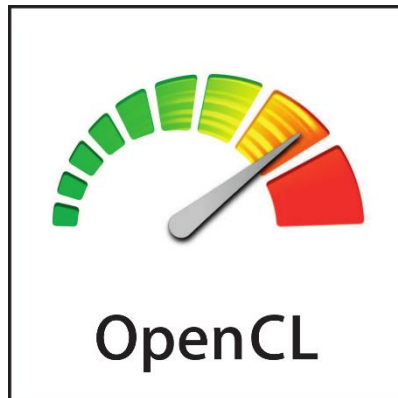
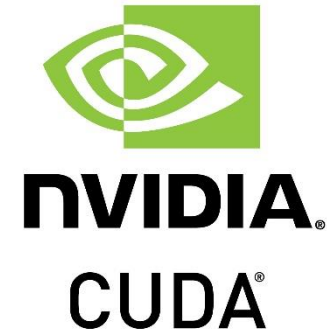
# EVALUATION OF MODERN GPGPU TECHNOLOGIES FOR IMAGE PROCESSING

JOACHIM MEYER  
IMAGE PROCESSING  
GPGPU ENGINEER



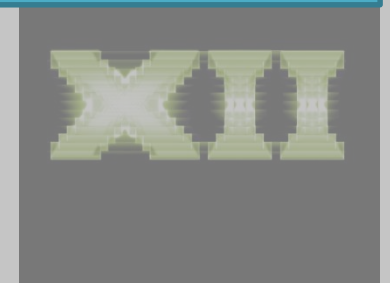
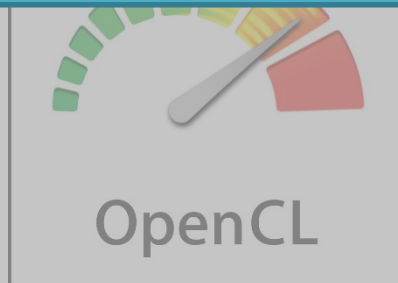
**VISION.  
RIGHT.  
NOW.**

# (TOO?) MANY DIFFERENT GPGPU PROGRAMMING MODELS / APIS



# (TOO?) MANY DIFFERENT GPGPU PROGRAMMING MODELS / APIS

Which one fits this  
awesome new project?



```

read_accessor inAcc_;
write_accessor outAcc_;

SizeXY size_;
SizeXY outSize_;

PlaneExtractWorker(SizeXY size, SizeXY outSize, read_accessor in, write_accessor out)
: inAcc_(in), outAcc_(out), size_(size), outSize_(outSize){}

void operator()(sycl::nd_item<2> itm)
{
    size_t x = itm.get_global_id(0), y = itm.get_global_id(1);

    if(x >= (outSize_[0] / 2) || y >= (outSize_[1] / 2))
        return;

    size_t xIn = (itm.get_global_id(0) + 1) * 2, yIn = (itm.get_global_id(1) + 1) * 2;

    size_t row = xIn + (yIn - 1) * size_[0];
    typename dt::tmp_vec4 line0{inAcc_[row - 1], inAcc_[row], inAcc_[row + 1], inAcc_[row + 2]};

    row = xIn + (yIn) * size_[0];
    typename dt::tmp_vec4 line1{inAcc_[row - 1], inAcc_[row], inAcc_[row + 1], inAcc_[row + 2]};

    row = xIn + (yIn + 1) * size_[0];
}

```



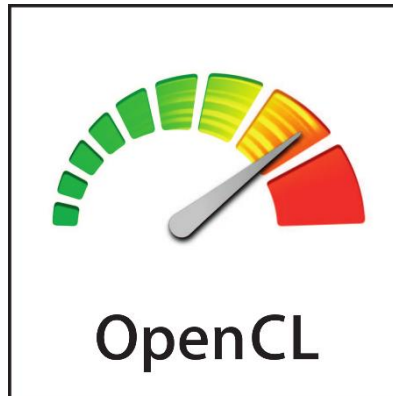
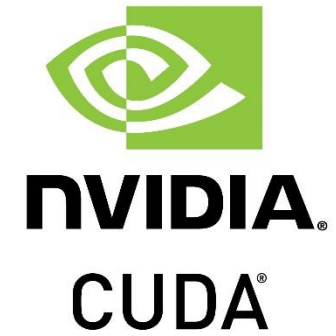
# AGENDA

- SELECTION OF COMPARED APIS
- EVALUATION SETUP
- PERFORMANCE
- USABILITY
- PLATFORM INDEPENDENCE
- CONCLUSION
- FUTURE PROSPECTS

# BASICS

---

Selection of APIs



# BASICS

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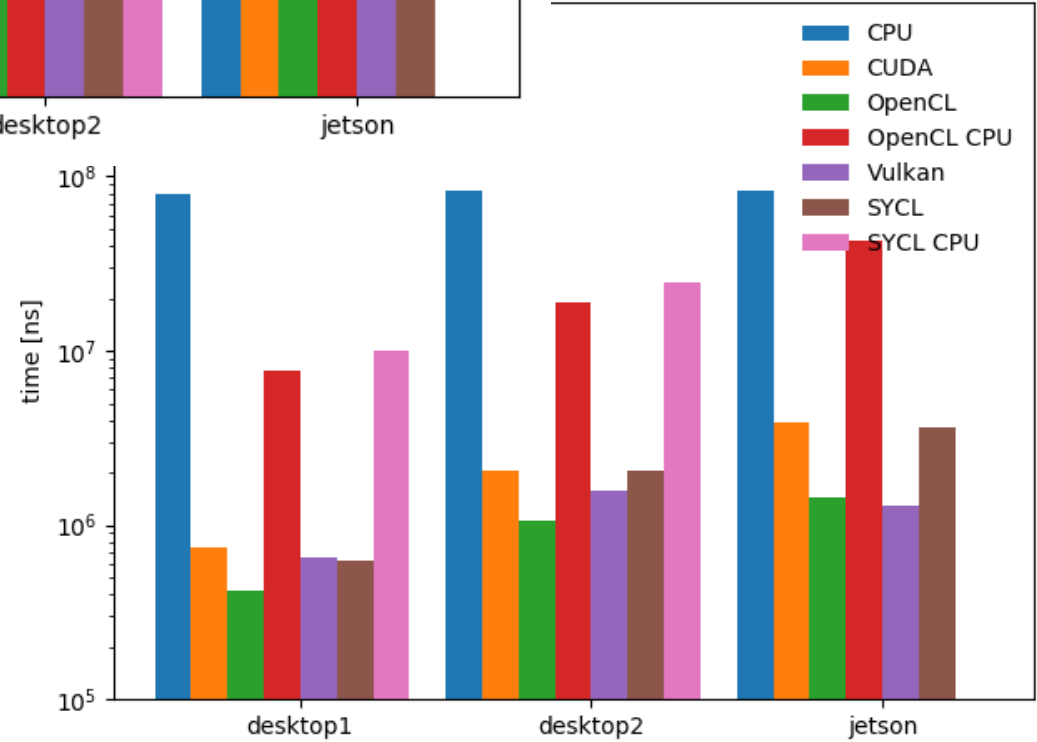
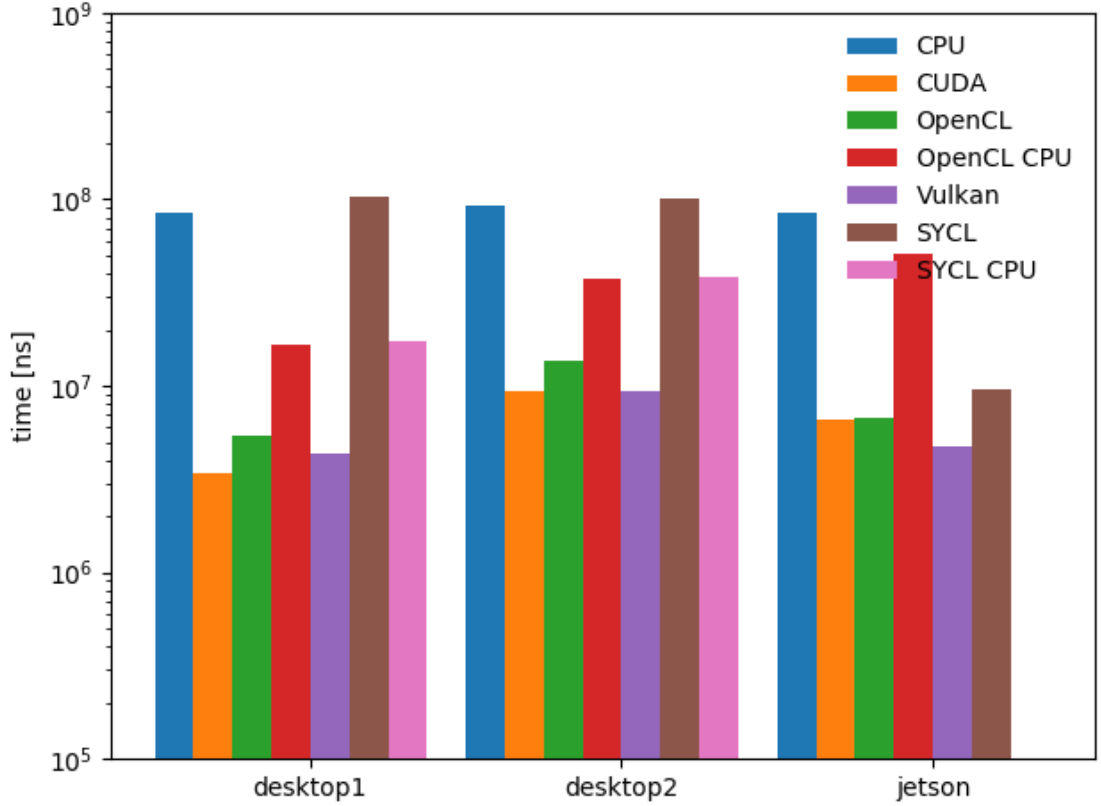
## Test Project setup

- Targeting all 4 APIs + CPU reference implementation
- Targeted devices: CPUs & GPUs
- OSs: Windows & Linux 64bit
- Implementations:
  - CUDA 10.1
  - Vulkan 1.1
  - OpenCL 1.2
  - ComputeCpp (Win) & hipSYCL (Linux)
- Algorithms for polarization camera image processing



It's comparable.

# PERFORMANCE



How hard is it?

# USABILITY

```

std::ifstream ifs(sourceDir.string(), std::ios::binary | std::ios::in | std::ios::ate);
if(!ifs.is_open())
{
    throw std::runtime_error("Could not find or open file\n");
}

size_t size = ifs.tellg();
ifs.seekg(0, std::ios::beg);

std::uint32_t filesizepadded = static_cast<std::uint32_t>(ceil(size / 4.0) * 4);

// read file contents.
char *str = new char[filesizepadded];
ifs.read(str, size);
ifs.close();

// data padding.
for(size_t i = size; i < filesizepadded; i++)
{
    str[i] = 0;
}

length = filesizepadded;
return (uint32_t *)str;
}

public:
Shader(vk::UniqueShaderModule &module, spirv_cross::Parser &ir) :
    module_(std::move(module)), ir_(std::move(ir)) {}

Shader(const Shader &) = delete;
void operator=(const Shader &) = delete;

Shader(Shader &rhs)
    : module_(std::move(rhs.module_)), ir_(std::move(rhs.ir_)) {}

Shader &operator=(Shader &rhs)
{
    module_ = std::move(rhs.module_);
    ir_ = std::move(rhs.ir_);
    return *this;
}

vk::ShaderModule &ShaderModule()
{
    return *module_;
}

static Shader FromGlsLFile(std::string path, std::vector<std::pair<std::string, std::string>> macros, SharedVulkanProvider provider)
{
    shaderc::Compiler compiler;
    shaderc::CompileOptions opts;
    for(auto macro : macros)
    {
        opts.AddMacroDefinition(macro.first, macro.second);
    }

    opts.SetTargetEnvironment(shaderc_target_env_vulkan, shaderc_env_version_vulkan_1_1);
    opts.SetOptimizationLevel(shaderc_optimization_level::shaderc_optimization_level_performance);
    opts.SetIncluder(std::make_unique<ShaderIncluder>());
    auto source = SourceFile::FromFile(path);

    auto result = compiler.CompileGlsLToSpirv(source.Source(), shaderc_shader_kind::shaderc_compute_shader, path.c_str(), "main", opts);
    if(result.GetCompilationStatus() != shaderc_compilation_status_success)
    {
        throw compilation_error{std::string("Compiling ") + path + std::string(" failed with:\n") + result.GetErrorMessage()};
    }

    std::vector<std::uint32_t> binary(result.cbegin(), result.cend());

    vk::ShaderModuleCreateInfo createInfo({}, binary.size() * 4, binary.data());

    auto module = provider->CreateShaderModule(createInfo);
    auto parser = spirv_cross::Parser(std::move(binary));
    parser.parse();

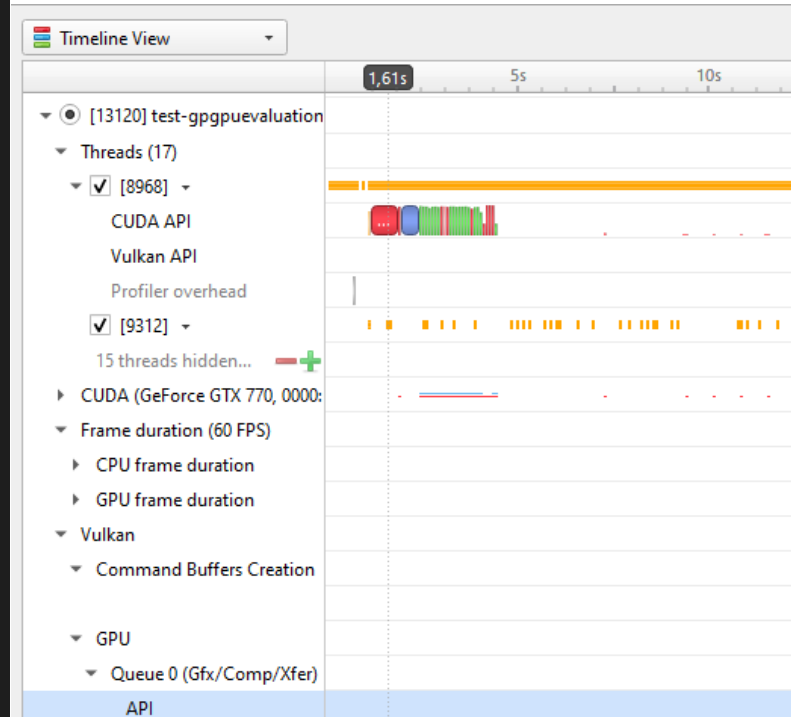
    return {std::move(module), std::move(parser.get_parsed_ir())};
}

static Shader FromFile(std::string path, SharedVulkanProvider provider)
{
    std::uint32_t size;
    std::uint32_t *shaderData = readFile(size, path);
    vk::ShaderModuleCreateInfo createInfo({}, size, shaderData);

    auto module = provider->CreateShaderModule(createInfo);
    spirv_cross::Compiler comp(shaderData, size);
    delete[] shaderData;

    auto parser = spirv_cross::Parser(shaderData, size);
    parser.parse();

    return {std::move(module), std::move(parser.get_parsed_ir())};
}
};
// namespace Vulkan
// namespace @GPUevaluation
    
```





# WHAT'S THE IMPLEMENTATION COST?

	CUDA	SYCL	OpenCL	Vulkan
LoC basic setup	4	5	6	65
LoC realistic setup	25	27	34	128 (+ 25 GLSL→SPIRV)
LoC / new kernel	4	5	6	11
C++ kernels	✓	✓	✓	
Implicit asynchrony	✓	✓	✓	
Taskgraph	✓	✓		

# ANY TOOLS TO HELP?

## CUDA

- Solid dev tooling:
  - kernel debugging
  - profiling
  - IDE integration

## SYCL

- Hardly any specific tools, but native OpenCL / HIP tools usable
- Host-device enables native IDE debugging

## OpenCL

- Mostly vendor specific dev tools
- LPGPU<sup>2</sup> CodeXL: generalization of AMD project

## Vulkan

- Mainly graphics focused tooling
- Validation layers
- Emulator (Talvos)

# LIBRARIES?

## CUDA

- Many optimized libraries
- FFT, BLAS, image processing, ...

## SYCL

- Some libraries
  - BLAS, DNN, RNG, Parallel STL, image processing
  - Native (OpenCL / HIP) libraries usable

## OpenCL

- Number of libraries with some device-specific optimization
- FFT, BLAS, DGEMM, image processing, ...

## Vulkan

- Hardly any Compute specific libraries

# HELP ANYONE?

## CUDA

- Widely used by scientists and application devs
- De-facto standard in ML libraries

• SO Questions: 12.380

## SYCL

- Few applications known
- Tensorflow
- Eigen

• SO Questions: 28

## OpenCL

- Wide adoption in consumer applications
- Adobe Creative Cloud
- Final Cut Pro

• SO Questions: 5.040

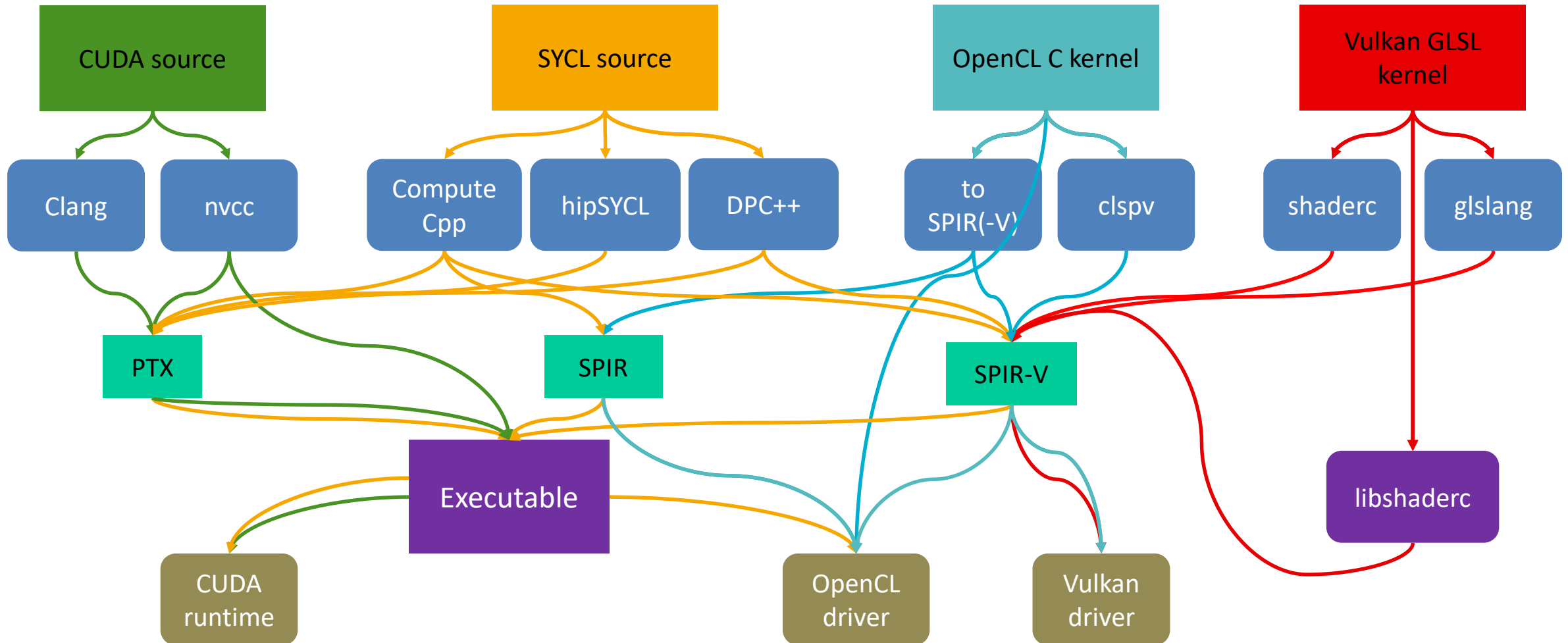
## Vulkan

- Increasing adoption for mobile device support / combined with graphics
- Adobe Premier Rush
- OcataneRender

• SO Questions: 1.020

EACH API HAS ITS OWN (KERNEL) COMPILATION WORKFLOW

# HOW DOES THE CODE COME TO LIFE?



# HOW TO HANDLE DYNAMIC DATA TYPES?

CUDA

Generic programming

SYCL

Generic programming

OpenCL

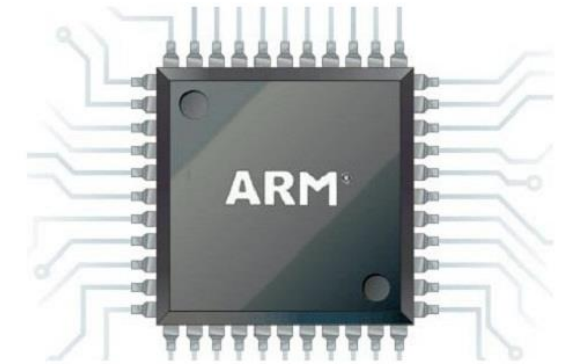
(Dynamic) online  
compilation with  
required data type as  
macro

Preprocessor  
programming to dispatch  
temporary data types

Vulkan

Online / offline  
compilation with  
required data type as  
macro / in shader names

Preprocessor  
programming to dispatch  
temporary data types



Can it target XYZ?

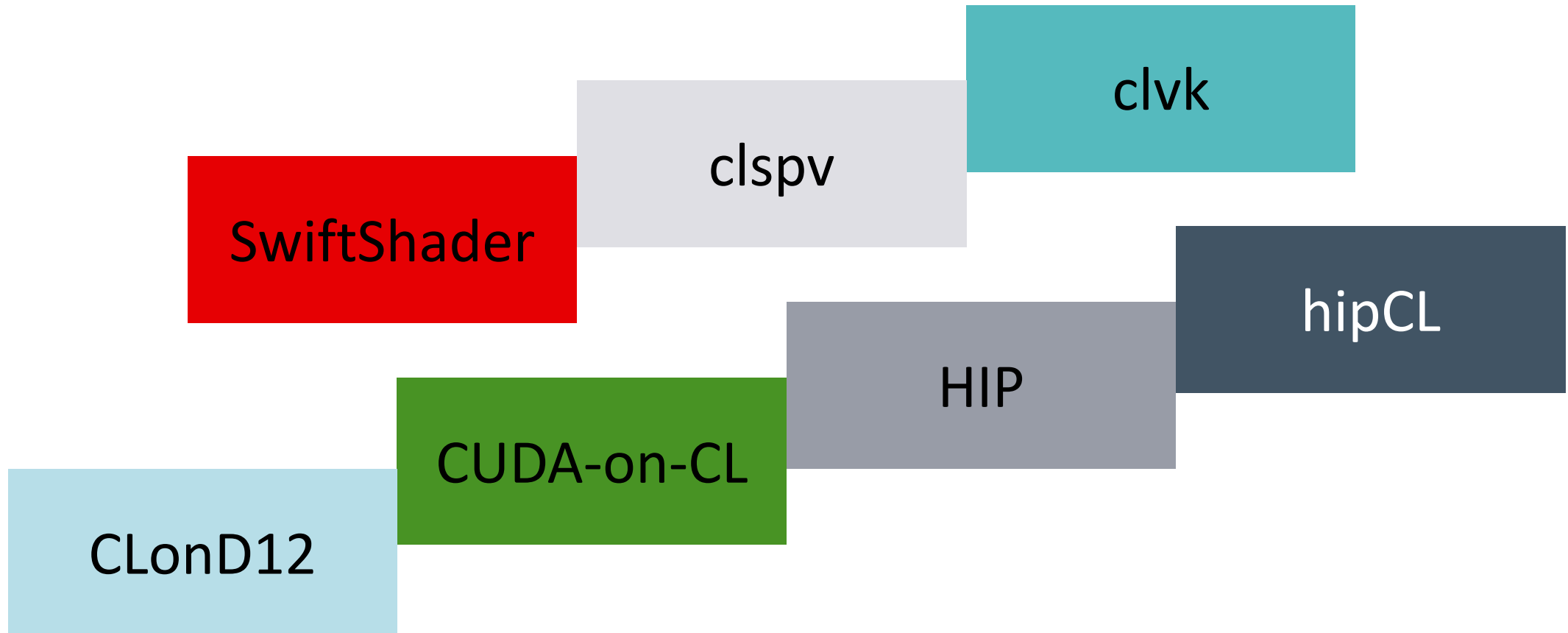
# PLATFORM INDEPENDENCE



# CAN IT TARGET XYZ?

	CUDA	SYCL	OpenCL	Vulkan
Most recent version	10.2	1.2.1	2.2	1.2
Nvidia	10.2	1.2.1	1.2	1.2
AMD	HIP	1.2.1	2.0	1.2
Intel		1.2.1	2.1	1.2
ARM		1.2.1	2.1	1.2
Windows	✓	✓	✓	✓
Linux	✓	✓	✓	✓
macOS	✓		✓	✓
Android			✓	✓
CPU		✓	✓	✓
FPGAs		✓	✓	

# PORTABILITY INITIATIVES



# CONCLUSION

So which API should be used?

CUDA	SYCL	OpenCL	Vulkan
Single-source programming	Single-source programming	Cross-platform (incl. FPGAs,..)	Fully OS and GPU-vendor independent
Highly optimized and powerful libraries and tools	Multi-platform (incl. FPGAs,..)	Mature libraries	High setup cost but possibility to optimize
Vendor lock-in acceptable? (Maybe use HIP instead?)	Tools for underlying implementation usable	Big community	Lack of compute specific tooling & libraries
	Emerging SYCL-specific tool and library support	Not-up-to-date implementations	

# FUTURE PROSPECTS



# WHAT'S UP NEXT?

## CUDA

- Extended ARM & data-center support
- Continuous optimization and feature updates
- Fast support for new GPU features
- HIP porting to Windows?

## SYCL

- Maturing and optimization of implementations
- Extended hardware and OS support
- Removal of OpenCL as conformance required backend
- Specific tooling and libraries
- News @ IWOCL
- SYCL-on-Vulkan?

## OpenCL

- (Hopefully) improved vendor support with OpenCL Next
- Updated to new hardware features
- Higher-level kernel language support
- News @ IWOCL

## Vulkan

- Continued wide support
- Extended compute capabilities to serve as portability backend for other APIs
- Compute specific libraries & tools
- Fast support for new GPU features

# THANK YOU VERY MUCH FOR YOUR ATTENTION

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